

# POWER QUALITY IMPROVEMENT USING ACTIVE FILTERS: A REVIEW

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## **ABSTRACT**

*This paper covers review of the various configurations and control strategies available for active filters. Various configurations of APFs have been proposed to compensate aforementioned power quality problems. Complexity of the control algorithm can also be reduced with the involvement of artificial intelligence like fuzzy logic, neural network etc. with the conventional approach to resolve the poor power quality problems not only in steady-state but also in dynamic/transients situation.*

**Keywords:** *Active Power Filter (APF), Harmonics, Power Quality, Nonlinear, Reactive Power Compensation.*

## **I. INTRODUCTION**

The widespread use of non-linear loads in industries and extensive proliferation of energy-efficient power electronic based equipment's have led to many power quality problems in electrical power system and becoming a great concern for utilities and customers. These Non-linear loads draw harmonics and reactive power (VARs) components of current from the utility. In three-phase systems, they could also induce imbalance and draw excessive neutral current. All these issues create serious problems for power quality.

The effective compensation of harmonics, reactive power, neutral current and supply current balancing with other power quality improvement are essential for the utilities as well as the end users. This attracted power electronics and power system engineers to develop dynamic and adjustable solutions to the power quality problems by various custom power devices like active power filter (APF), hybrid filter, unified power quality compensator (UPQC) etc. Many control algorithms with new / improved designs are presented by various researchers in context to this. In this paper a review on the various topologies and control strategies of active filters is presented.

This paper is presented in five sections. First section introduces the power quality issues followed by sections on technologies used in APFs to resolve them, classification of APFs based on converter type, topologies and number of phases and various control strategies. At last, conclusion along with future scope is presented.

## **II. ACTIVE POWER FILTERS**

Many passive and active harmonic filters have been investigated to satisfy the power quality problems. Passive filtering has been preferred for harmonic compensation in the electrical system due to low cost, simplicity, reliability, and control less operation. Active power filters (APF) have many advantages over the passive filters.

They can suppress not only the supply current harmonics, but also the reactive currents and without causing harmful resonances with the power distribution systems like passive filters.

In the beginning, the APFs were used for suppression of harmonics generated by thyristor based converters and inverters used in HVDC transmission system. However, the design could not become technologically and economically practicable until the last two decades when fast and cost effective semiconductor devices such as Insulated Gate Bipolar Transistors (IGBTs) and Metal Oxide Semiconductor Field Effect Transistors (MOSFETs), and high performance and cost effective Digital Signal Processors (DSPs) became available. Modern active filters are superior in filtering performance since they inject voltage / current harmonics produced by nonlinear loads of same magnitude but of opposite sign so they cancel each other and sinusoidal waveforms are obtained at the power line. Depending on the APF type, controllable reactive power compensation for power factor correction, voltage regulation, load balancing, voltage-flicker reduction, harmonic damping, harmonic isolation and / or their combinations could be provided.

Now a day's improved control strategies for AF with design of high efficiency and large capacity converters has been developed for three-phase three- or four- wire power circuit. These wide ranges of objectives are achieved either individually or in combination, depending upon the requirements and control strategy and configuration which have to be selected appropriately.

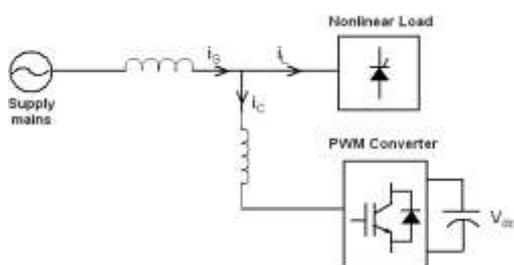
With the revolution in microelectronics, microprocessors, microcontrollers, DSP technology and with the advent of fast self-commutating solid-state devices like IGBTs and sensor technologies have enhanced performance of active filter. This paper presents various types of active filters and their classification based on topologies, control strategies and number of phases and brief explanation of mainly used techniques.

### III. CLASSIFICATION OF ACTIVE POWER FILTERS

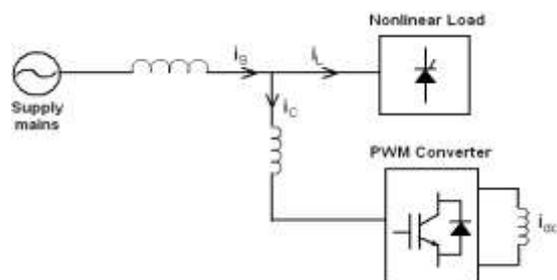
Active Filters can be classified based on converter type, topologies and number of phases. On converter based CSI or VSI bridge structure. On topology based shunt, series, hybrid and UPQC. On the bases of no. of phases two-wire (single phase) and three- or four-wire three-phase systems.

#### 3.1 Converter Based Classification

In general, there are two types of converters used in active filters - CSI or VSI bridge structure. A current source PWM converter (CSI) is equipped with a dc inductor and a voltage source PWM converter (VSI) is equipped with a dc capacitor. Fig.1. shows CSI bridge structure.



**Fig. 1 Voltage Source PWM Converter Based Shunt Active Power Filter**

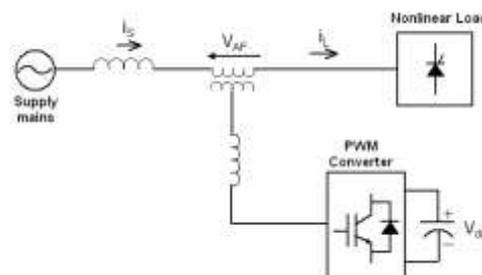


**Fig. 2 Current Source PWM Converter Based Shunt Active Power Filter**

Fig.2. shows VSI based filter that has a self-supporting dc voltage bus with a DC capacitor. It becomes dominant over CSI because of its high efficiency, lightweight, low cost and expandability to multilevel and multi-step versions.

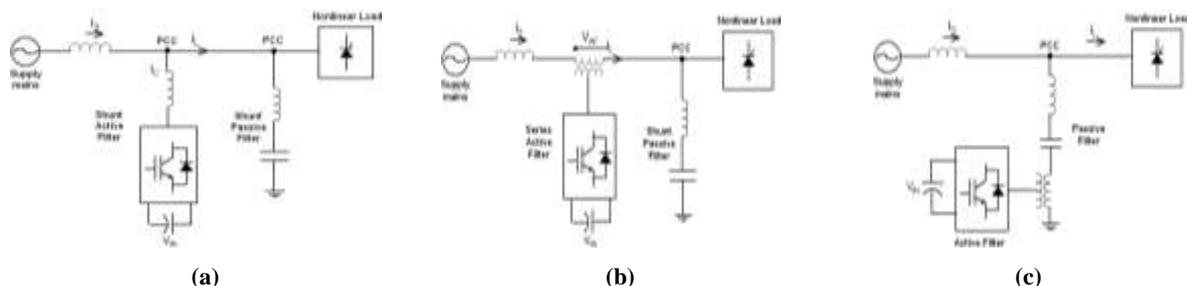
### 3.2 Topologies Based Classification

Based on the topology, AF can be classified as series, shunt, hybrid active filters and UPQC. The appropriate topology is used as per the compensation required by the active filter. Parallel or shunt APF is the fundamental system configurations and it has been used in of three-phase three- or four- wire. Fig. 1 and 2 shows shunt APF, which consists of a controllable voltage and current source respectively. It is mainly used to eliminate current harmonics, reactive power compensation and balancing unbalanced input currents. Shunt active filters carries only the compensation current plus a small amount of active fundamental current which is supplied to compensate for system losses. This cancels harmonics and/or reactive components of the nonlinear load current at the point of common coupling (PCC). When it is employed to three-phase four-wire systems, it also compensates the neutral current (zero sequence current) component.



**Fig. 3 Principle configuration of a VSI based series active power filter**

Series active filter produces a PWM voltage waveform which is subtracted / added, on an instantaneous basis, from / to the supply mains voltage to maintain a pure sinusoidal voltage waveform across the load as shown in Fig. 3. It is similar to shunt APF, except that the interfacing inductor of shunt APF is replaced with the interfacing transformer. Its advantage over shunt active filters is that they are superlative for eliminating voltage-waveform harmonics, and for balancing three-phase voltages



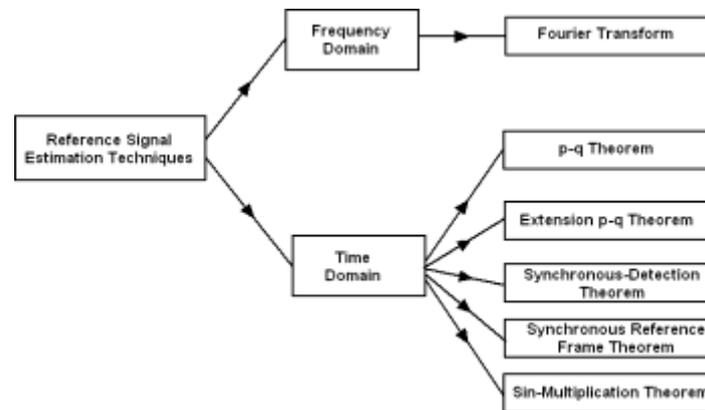
**Fig. 4 Hybrid Active Filter In Combination With**

- (a) Shunt Active and Shunt Passive Filter, (b) Series Active and Shunt Passive Filter, And  
 (c) Active Filter Connected In Series With Shunt Passive Filter.**

Hybrid active filter configurations are typically the combination of basic active shunt / series and a passive filter. Hybrid APFs inherits the advantages of both active and passive filters. The active filter cancels the lower order harmonics, while the passive filter is responsible for higher order harmonics. Therefore, the main objective of hybrid active filter is to improve the filtering performance of high-order harmonics while providing



accurate, and it should give its best performance not only in ideal voltage condition but also in distorted and/or distorted and unbalanced voltage condition which are normally present in the electrical distribution system. Proper estimation of compensating signal for achieving particular compensation objectives also affects the steady-state and transient performance of the APFs. Broadly, control strategies for compensating signals generation are based on frequency-domain or time-domain techniques. Fig.6. illustrates the general classification of available techniques.



**Fig. 6 Classification of Reference Signal Estimation Techniques**

Both frequency-domain and time domain techniques have been used with VSI and CSI PWM converters. In recent research new methods based on wavelet transform and Artificial Intelligence (AI) are also reported for extraction of reference signal.

#### **4.2.1 Frequency Domain Approach**

In this, reference signal estimation in frequency-domain is suitable for both single and three phase systems. The frequency domain methods are based on Fourier analysis method of discrete signals such as Discrete Fourier Transform (DFT, and Fast Fourier Transform (FFT) and periodicity of distorted voltage and/or current waveforms to be corrected. Its major drawback is the requirement of a window function to analyze the frequency spectrum of the signal; this method also suffers from large memory requirement and large computational power for processor used. To eliminate higher harmonics number of calculations increases, which results in large response time and also not suitable for dynamically varying loads. Although the modified Fourier transform based methods adopting the sliding window show an improved dynamic response. Recent development in the processor technology is helping in reducing the computational time.

#### **4.2.2 Time Domain Approach**

This approach is based on instantaneous estimation of reference signal in the form of either voltage or current signal from distorted and harmonic-polluted voltage and current signals. The main advantages of the time domain compensation is its fast response, easy implementation and less computational burden. There is a large number of control methods in the time domain, which are known as instantaneous “p–q” theory, synchronous d–q reference frame method, synchronous detection method, flux-based controller, notch filter method, P–I controller, sliding mode controller, etc.

#### **4.2.3 Control Based on Artificial Intelligence (AI)**

AI is a technology to extract information from the process signal by using expert knowledge. Artificial intelligence is popular due to its ability to handle nonlinearity, complex problem without much information

about the mathematical model of the system. It can identify the model, if necessary, and give the predicted performance even with a wide range of parameter variation. Different tools of AI such as fuzzy logic, artificial neural network, genetic algorithm, wavelet theory, etc. are used in various applications of power quality and power electronics for improving the robustness and performance of control algorithm

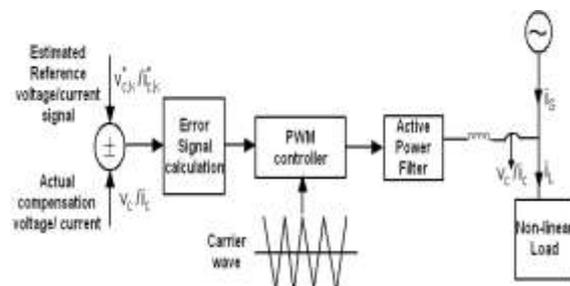
### 4.3 Generation of Gating Signal to Control Switches

Once the compensation signals are obtained based on the appropriate control scheme, the next stage of APF control is the generation of switching signals for the switching devices of the PWM converter. These switching signals are obtained by comparing the reference compensating current signals with the actual current in a controller. The switching patterns decide the required compensation of current harmonics. There are different control techniques for generation of gating signals. The performance of an APF is significantly affected by the selection of control techniques.

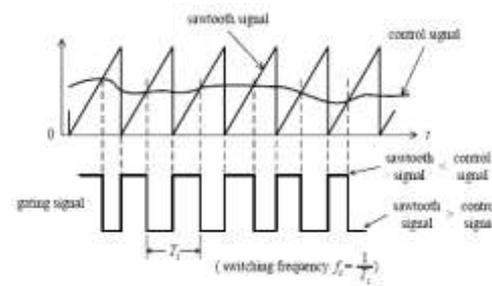
In linear control technique, voltage or current PWM, sinusoidal internal model control, ramp comparison control, etc. are used for obtaining the PWM signals. Nonlinear current control techniques include hysteresis control and SVM. In this section, a brief description of mostly used PWM techniques and their features have been presented.

#### 4.3.1 Voltage or Current PWM Technique

Linear control technique of switching pulse generation for APF semiconductor switches is accomplished by using a negative feedback system as shown in Fig. 8.



**Fig. 8 Block Diagram of Linear Control Technique Linear Control**

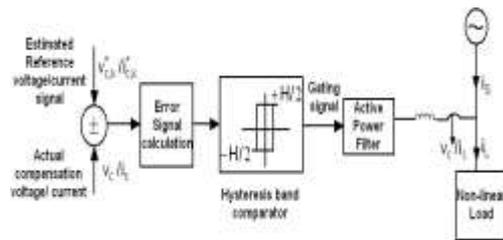


**Fig. 9 Generation of Gate Signals Using Technique**

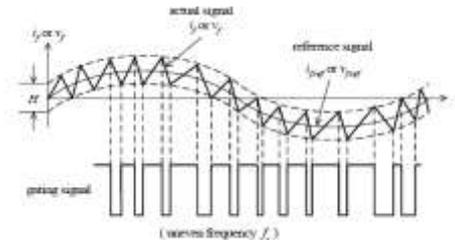
voltage  $v_c$  signal is compared with its estimated reference signal ( $i_{c,ref}$  and  $v_{c,ref}$ ) through the Compensated error amplifier to produce the control signal. The resulting control signal is then compared with a fixed frequency carrier (triangular or ramp) signal. The frequency of the repetitive carrier signal establishes the switching frequency. This frequency is kept constant in linear control technique. As shown in Fig. 9, the gating signal is set high when the control signal has a higher numerical value than the carrier signal and vice versa.

#### 4.3.2 Hysteresis Control Technique

This technique forces the compensating current  $i_c$  or voltage  $v_c$  signal to follow its estimated reference signal ( $i_{c,ref}$  or  $v_{c,ref}$ ) within a specified tolerance band, known as hysteresis-band. Switching occurs whenever the error leaves the tolerance band. A basic block diagram of the hysteresis band current control is shown in Fig. 10.  $H$  is the hysteresis-band. The APF is switched on in such a way that the peak-to-peak compensation current/voltage signal is limited to a specified band ( $H$ ) as illustrated in Fig. 11.



**Fig. 10 Block Diagram of Hysteresis Control Technique**



**Fig. 11 Gating Signal Generation By Hysteresis Controller**

The advantages of using the hysteresis current controller are its excellent dynamic performance and controllability of peak-to-peak current ripple within a specified hysteresis band. The main drawback of this technique is that it produces uneven switching frequency, which affects the APF efficiency and reliability.

### 4.3.3 Space Vector Modulation (SVM)

This method has several benefits like better voltage utilization, lesser current harmonics, and fixed frequency operation. Although implementation of SVM in digital system is simple, the required calculations and corresponding execution time limits the maximum sampling time and resulting maximum switching frequency and maximum bandwidth. It is reported that hysteresis current control technique is found superior and its performance is almost unaltered by the variation in the firing angle. In direct current control technique APF currents are used as reference compensating current ( $i_{ca}^*, i_{cb}^*, i_{cc}^*$ ) which further compared with actual filter current ( $i_{ca}, i_{cb}, i_{cc}$ ). Reference compensating current are obtained by subtracting load current from the reference supply current and therefore need more number of current sensors. In indirect current control technique the switching signals are obtained by the comparison of estimated reference source current ( $i_{sa}^*, i_{sb}^*, i_{sc}^*$ ) with actual source current ( $i_{sa}, i_{sb}, i_{sc}$ ). It is experimentally verified that indirect current control technique is simpler, requires less hardware and offers better performance. It is also capable of eliminating the harmonics and switching ripples, resulting in sinusoidal supply current.

## V. CONCLUSION

After reviewing it is found that extensive efforts are being made to improve the performance of the APFs, with the help of new or improved modifications in topology and control methodologies. Various configurations of APFs have been proposed to compensate aforementioned power quality problems. Complexity of the control algorithm can also be greatly reduced with the involvement of artificial intelligence like fuzzy logic, neural network etc. with the conventional approach to resolve the poor power quality problems not only in steady-state but also in dynamic/transients situation.

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### BIOGRAPHICAL NOTES



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