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AUTOMATION AND TREATMENT OF SEWAGE PLANT

Miss. Rachana R. Sangitrao

Assistant Professor, Dept. of Instrumentation & Control, D. Y. Patil Engineering College, Akurdi, Pune, (India)

ABSTRACT

The term, Industrial Automation generally refers to the science and technology of process control of various plants such as chemical and petrochemical plants, oil refineries, iron and steel plants, power plants, paper pulp and paper mills, pharmaceutical, food and beverage industries, water and waste water treatment plants, oil and gas fields, etc. Plant Automation is one of the important requirements, which improves the quality of products as well as reduces requirements of manpower. Industrial automation has taken a giant step to control industrial machineries and industrial processes by replacing human operators. Now a day's Programmable Logic Controller (PLC) and SCADA systems are extensively used in industries. Industry people are encouraging use of Programmable Logic Controller (PLC) for plant automation. The origin of PLC comes from the American Automotive Industries. With the advent of industrial automation, we will briefly discuss the Programmable Logic Controller (PLC) used in our plant. This paper explains the work done for Automation of Sewage Treatment Plant using PLC and SCADA. In this work, we have used Schneider Electrics Controller and SCADA, Unity Pro XL and Vijeo-Designer software's.

Keywords: Programmable Logic Controller, Supervisory Control And Data Acquisition, Sewage Treatment Plant.

I INTRODUCTION

Automation: - Automation is the use of control systems and information technologies reduce the need for human work in the production of goods and services. In the scope of industrialization, automation is a step beyond mechanization. Whereas mechanization provided human operators with machinery to assist them with the muscular requirements of work, automation greatly decreases the need for human sensory and mental requirements as well. Automation plays an increasingly important role in the world economy and in daily experience. PLC and DCS are the most widely used tools.

1.1 Process Control is a statistics and engineering discipline that deals with architectures, mechanisms, and algorithms and for maintaining the output of a specific process within a desired range.

In old process controls, manual control of application was done where all the actions and decisions were done humans considering the errors, also with the help of hard wired logic.

Process control systems can be characterized as one or more of the following forms:

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- ✓ **Discrete**-Found in many manufacturing, motion and packaging applications. Robotic assembly, such as that found in automotive production, can be characterized as discrete process control. Most discrete manufacturing involves the production of discrete pieces of product, such as metal stamping
- \checkmark **Batch** Some applications require that specific quantities of raw materials be combined in specific ways for particular durations to produce an intermediate or end result. Batch processes are generally used to produce a relatively low to intermediate quantity of product.
- ✓ Continuous Often, a physical system is represented through variables that are smooth and uninterrupted in time. Continuous processes in manufacturing are used to produce very large quantities of product.

A commonly used control device called a Programmable Logic Controller, or a PLC is used to read a set of digital and analog inputs, apply a set of logic statements, and generate a set of analog and digital outputs. Larger more complex systems can be controlled by a Distributed Control System (DCS) or SCADA system.

Depending upon the larger complexity and the field wiring, control of field signals is done using these devices as per signals coming from devices and complexity of process.

To control the industrial machineries and processes we require some automation tools. Following are some automation tools used in the industries:

- 1. PLC Programmable Logic Controller
- 2. HMI Human Machine Interface
- 3. DCS Distributed Control System
- 4. SCADA Supervisory Control and Data Acquisition
- 5. LIMS Laboratory Information Management System
- 6. PAC Programmable Automatic Controller
- 7. MES Manufacturing Execution System

1.2 Programmable Logic Controller (PLC)

A Programmable Logic Controller commonly known as PLC is a digital computer used for automation of electromechanical processes, such as control of machinery on factory assembly lines, amusement rides, or lighting fixtures. PLCs are used in many industries and machines. Unlike general-purpose computers, the PLC is designed for multiple inputs and outputs arrangements, extended temperature ranges, immunity to noise, resistance to vibration and impact. The main difference from other computers is that PLC can be used in hazardous and severe conditions (dust, moisture, heat, cold, etc) and have the facility for extensive input/output (I/O). These connect the PLC to sensors and actuators.

The different manufacturers of PLC are listed below:

- **1.** Allen-Bradley
- 2. Siemens
- 3. Mitsubishi
- 4. Messung
- 5. GE Fanuc
- 6. Philips

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- **7.** ABB
- 8. Schneider electric
- 9. Omron

1.3 Human Machine Interface (HMI)

In the industrial design field of human –machine interaction, the HMI is the space where interaction between humans and machines occurs. The goal of interaction between a human and a machine at the user interface is effective operation and control of the machine, and feedback from the machine which aids the operator in making operational decisions. Examples of this broad concept of user interfaces include the interactive aspects of computer operating systems, hand tools, heavy machinery operator controls, and process controls. The design considerations applicable when creating user interfaces are related to or involve such disciplines as ergonomics and psychology.

A user interface is the system by which people (users) interact with a machine. The user interface includes hardware (physical) and software (logical) components. User interfaces exist for various systems, and provide a means of:

- Input, allowing the users to manipulate a system, and/or
- Output, allowing the system to indicate the effects of the users' manipulation.

Generally, the goal of human-machine interaction engineering is to produce a user interface which makes it easy, efficient, and enjoyable to operate a machine in the way which produces the desired result. This generally means that the operator needs to provide minimal input to achieve the desired output, and also that the machine minimizes undesired outputs to the human.

The different manufacturers of HMI are listed below:

- 1. Cursor Controls
- 2. Honeywell
- 3. Intech Systems
- 4. Nimbus Technologies
- 5. Renu Electronics
- 6. Schneider Electrics
- 7. Sima Tech Automation

II LITERATURE REVIEW

Programmable Logic Controllers (PLC) is a digital operational electronic device specially designed for working under industrial environment. The advantages of high reliability, good capacity and convenient operation make it widely used in automatic industrial control and electromechanical integration. And it is one of the backbones of industrial automation. And are dedicated systems used to control manufacturing processes that are continuous or batch-oriented, such as oil refining, petrochemicals, central station power generation, pharmaceuticals, food & beverage manufacturing, cement production, steelmaking, and papermaking. The survey and the literature are presented in this section.

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In order to ensure the sewage treatment equipment operation cycle and the suction pump intermittent work and realize automatic SBMBR sewage treatment equipment intelligently, this paper selected MITSUBISHI FX2N series PLC to introduce SBMBR sewage treatment system for control system. By analyzing of automatic control system targets, program design process is given. Eventually, designed automatic control system achieves automatically water stirring, water and control of anaerobic, anoxic, aerobic time. Automatic control system provides a reliable guarantee for the normal operation and effluent quality of SBMBR. The commissioning and operation practice has proved that system greatly improved the degree of automation and achieved good impact. [1]

Heavy metals Zn, Cu, Cd, Ni, Pb and Mn in the compressed sludge from Shenyang Northern Sewage Treatment Plant were removed by bioleaching. The results showed that: the treatment cycle of bioleaching was about 4d, water should be timely separated from sludge; After the treatment of bioleaching, the content of heavy metals in compressed sludge were below that of control standards for pollutants in sludge from agricultural use GB4284-1984, which indicated the sludge from the waste water treatment plant treated by bioleaching could be used as agricultural fertilizer; After the treatment of bioleaching, the existence forms of the six heavy metals were mainly restorable and oxidized state. These research results are very helpful to the dispose and reclamation of sludge from waste water treatment plant. [2]

III MODICON ARCHITECTURE

The System Architecture showed in figure is the main architecture of the Modicon PLC. In this system various PLC's are used such as Premium, Quantum, and Modicon M340, which uses Ethernet TCP/IP, for its communication purpose, and is the PLC I have use in my project, Ethernet, Hub, Modbus Bridge, Modbus TCP, Modbus Plus along with Quantum, 984, and Compact etc.



Figure 3.1: - Modicon PLC Architecture

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Fig 3.2 Configuration of Modicon PLC

The above setup is combination of with various components.

System Components:

- 3.1 Power Supply
- 3.2 Schneider controller
- 3.3 USB Programming Cable
- 3.4 Analog Input/Output
- 3.5 Digital Input/Output
- 3.6 Schneider HMI

IV SYSTEM MODEL

4.1 Principle of Operation

There are two different types of Biological processes for treating sewage. :

A. Aerobic Process

- 1. Suspended growth process
- 2. Attached growth process

B. Anaerobic Process

- 1. Suspended growth process
- 2. Attached growth process

The following fig 4.1 shows the generalized diagram of both processes. Here the attached growth process is used for treating the sewage under aerobic process so that the growth of microorganisms takes place in the membrane, therefore, here a media is used and that is plastic because of it's the growth of bacteria is obtained.

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Figure 4.1 Generalized Diagrams

4.2 Process Description

The Treatment Process is mainly based on the principle of FLUIDISED ATTACHED GROWTH PROCESS" and consists mainly of the following components:

MEDIA, which provides surface area for the growth of microorganisms.



AIR GRID SYSTEM, which ensures:

-High oxygen transfer efficiency to meet the oxygen demand exerted by the microorganisms.

-The fluidized state of the media

The system comprises of the following main units:

a) FAB reactor tank - I

b) FAB reactor tank - II

c) Tube Settler

Treatment stages:-

There are basically three different stages of treatment in the sewage treatment plant.

• Primary Treatment

The primary treatment basically involves physical treatment like screening and oil & grease removal.

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• Secondary Treatment

The secondary treatment is a biological process where the major COD & BOD reduction takes place. The biological treatment provided in this plant is a Fluidised Aerobic Bioreactor which is an attached growth process. After the biological treatment there is a chlorination system also provided which helps in disinfection. Normally as per the pollution control norms the secondary treated sewage can be disposed into the drainage line without any problem.

• Tertiary Treatment

In the tertiary treatment there are filters (DMF & ACF) provided to polish the treated sewage to the extent of reuse. Here the BOD & COD levels are further brought down so that the treated water can be now reused. This tertiary treated water can be reused in various applications like Car wash, Gardening, Cooling tower, etc. This water can also be recycled if required to further treat and use in other process applications. The treatment stages are diagrammatically represented in Fig 4.3 below.

V RESULT

All the inputs coming from field which are digital signal in the range of 0's and 1's, by using Ladder Diagram Language, Structural Text language. Structured text is a textual programming language that uses statements to define what to execute. i. e. we can assign tag: = expression; (tag: = %IW0.1.0 Data); for input. And (%QW0.2.0 Data: = tag) for output.





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(FAB-Based) Sewage Treatment Plant

The sewage treatment is a typical process of treating the waste which is obtained from almost all domestic complexes, Hospitals, Institutes, Malls, Offices, Industries, Schools, Marine, etc. It consists of a FAB (Fluidized Aerobic Bioreactor) which works on the principle of attached growth process which uses plastic as a media in it so that the microorganisms may grow which is the main cause in this membrane. Table 5.1 shows the temperature parameters and time of tests carried out at plant site.



Figure 5.1(a): - Digital Input Mapping Using Structural Text Programming

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Structural view	Variables DDT Types Function	Blocks DFB Types			
(P) (P) : BMX CP5 2010	Name	X		EDT DDT	IODDT
0 : BMX P34 1000 Control Dark	Name	▼ Type ▼	Address 🔹	Value Commen	xt -
SenaiPort	SPARE2 START	EBOOL	%00.2.24		
1 : DPA DD1 0402K	AB_1011_LOCAL_ENAB	LED EBOOL	%Q0.2.25		
3 : BMX DDM 16022	AB_1012_LOCAL_ENAE	LED EBOOL	%Q0.2.26		
4 · BMY AMI 0410	AB_1021_LOCAL_ENAE	LED EBOOL	%Q0.2.27		
5 : BMX AMI 0410	AB_1022_LOCAL_ENAE	LED EBOOL	%Q0.2.28		
6 : BMX AMO 0410	P_1011_LOCAL_ENABL	ED EBOOL	%Q0.2.29		
7	P_1012_LOCAL_ENABL	ED EBOOL	%Q0.2.30		
Derived Data Types	P_1021_LOCAL_ENABL	ED EBOOL	%Q0.2.31		
Derived FB Types	P_1022_LPBS_MODE_E	NABLE EBOOL	%Q0.2.32		
Variables & FB instances	P_1031_LPBS_MODE_E	NABLE EBOOL	%Q0.2.33		
Elementary Variables	P_1032_LPBS_MODE_E	NABLE EBOOL	%Q0.2.34		
Derived Variables	P_1041_LPBS_MODE_E	NABLE EBOOL	%Q0.2.35		
IO Derived Variables	P_1042_LPBS_MODE_E	NABLE EBOOL	%Q0.2.36		
Elementary FB Instances	P_1051_LPBS_MODE_E	NABLE EBOOL	%Q0.2.37		
Derived FB Instances	P_1052_LPBS_MODE_E	NABLE EBOOL	%Q0.2.38		
Motion	P_1061_LPBS_MODE_E	NABLE EBOOL	%Q0.2.39		
Communication	P_1062_LPBS_MODE_E	NABLE EBOOL	%Q0.2.40		
	P_1071_LPBS_MODE_E	NABLE EBOOL	%Q0.2.41		
Tasks	P_1072_LPBS_MODE_E	NABLE EBOOL	%Q0.2.42		
🖃 🔄 MAST	AG_1050_LOCAL_ENAE	LED EBOOL	%Q0.2.43		
🗄 🦳 🤤 Sections	AGT_2040_LOCAL_ENA	BLED EBOOL	%Q0.2.44		
LD MAPPING	AGT_1100_LOCAL_ENA	BLED EBOOL	%Q0.2.45		
AUTO	HALF_OUT_SCREEN_L	OCAL_ENABLED EBOOL	%Q0.2.46		
MANUAL	CF_1010_LOCAL_ENAB	LED EBOOL	%00.2.47		
SCALING	SPARE1_LOCAL_ENAB	LED EBOOL	%00.2.48		
OUTPUT	SPARE2_LOCAL_ENAB	LED EBOOL	%UU.2.49		
FAULTS	MPV1_START	EBOOL	%UU.2.50		
SR Sections	MPV2_START	EBOOL	%QU.2.51		
Events					►
Animation Tables					
🥌 Operator Screens 🛛 😽	Data Editor 💷 PLC bus				
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Figure 5.1 (b): - Digital Output Mapping Using Structural Text Programming

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All the inputs coming from field which are digital signal in the range of 0's and 1's, by using Structural Text language. Structured text is a textual programming language that uses statements to define what to execute. i. e. we can assign *tag:* = *expression;* (tag: = %IW0.4.0 Data); for input and (%QW0.4.4 Data) for output.



Figure 5.2: - Analog Input Output Mapping Using Structural Text Programming

Sr. No.	Mode of operation	Temperature ⁰ C	Time minutes
1	Filtration	120°C	10
2	Cooling	50°C	13
3	Heating	123.5°C	19
4	Cooling	48.5°C	18
Total Time in Minutes			65
1	Heating	122.5°C	14
2	Cooling	45.5°C	12
3	Heating	120°C	16
4	Cooling	47.5°C	13
Total Time in Minutes			55

In the deareator tank, the differential pressure depends on level. Example set pressure parameter to 0.06 bars for level set parameter to 53%.

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Deareator			
Sr. No.	Temperature ⁰ C	Level %	Pressure bar
1	55	53%	0.06 bar
2	70	65%	0.05 bar

Table 5.2 Deareator Tank Parameters

Clean-In-Place (CIP) Process

In the CIP preparation, conductivity parameter is very important factor, conductivity parameter at 100Ms/cm2 for temperature 67.5 0C.

	CIP Preparation		
Sr. No.	Conductivity Ms/cm2	Temperature ⁰ C	
1	100 Ms/cm2	67.5 ^o C	
2	75 Ms/cm2	65 ⁰ C	
3	73 Ms/cm2	64.5 ⁰ C	

Table 5.3 CIP Preparation Process Parameters

In the CIP supply, the flow rate of solution with conductivity and temperature is required for CIP of tanks. Example set Flow rate parameter at 10,150 LPH with temperature $64.^{0}$ C.

CIP Supply				
Sr. No.	Flow Rate LPH	Temperature ⁰ C	Conductivity Ms/cm2	
1	10,150 LPH	64.5 ° C	73 Ms/cm2	
2	10175 LPH	67.5 ° C	100 Ms/cm2	
3	10,000 LPH	65 ⁰ C	75 Ms/cm2	

Table 5.4 CIP Supply Process Parameters

When the parameters were set as per the above tables, it was observed that the plant achieved desired performance. For example in sterilization process, set temperature parameter for the heating mode at 123.5 ^oC to maintain this temperature for 19 minutes to sterilize the material.

VI CONCLUSION

Hybrid Distributed Control system covers the direct automation of the Industrial process and machines, spanning the integration of sensors, controllers, and man machine interface in to control system that had handled the moment to moment demands of the process operation.

After Factory Acceptance Test, we found that the application control module is working satisfactorily and process can be operated in Auto Mode according to the control philosophy given by Alfa Laval (I) Ltd., Pune to Analogic Automation, Pune using Hybrid DCS and SCADA.

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